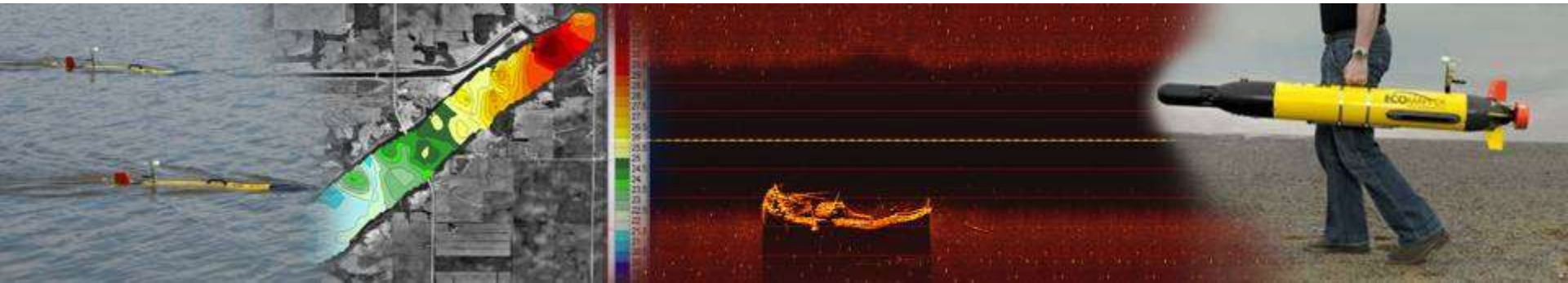


YSI EcoMapper

Autonomous Underwater Vehicle

~ A Cost-Effective Water Quality & Bottom Mapping Tool ~



ECOMAPPER
Autonomous Underwater Vehicle

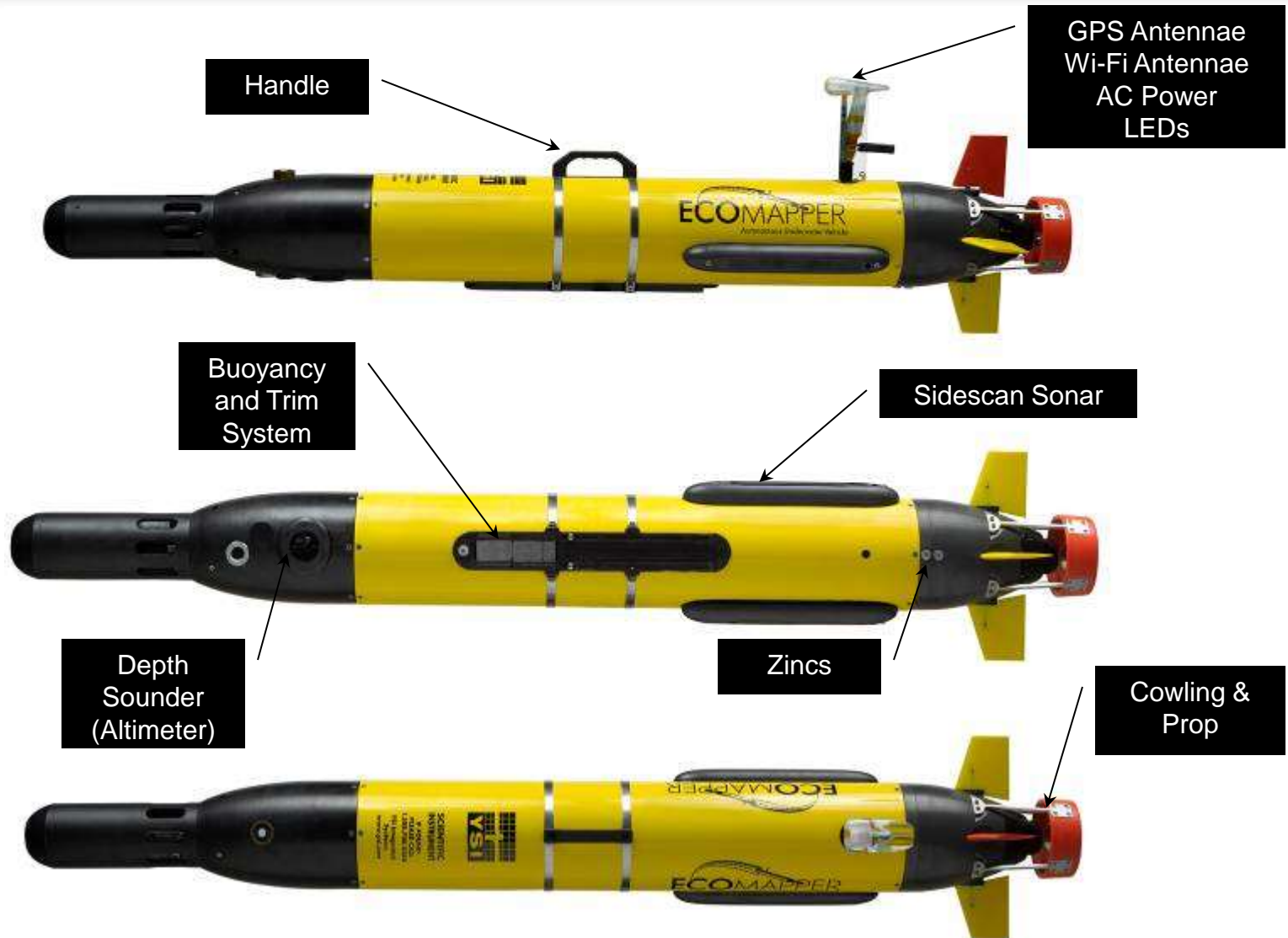


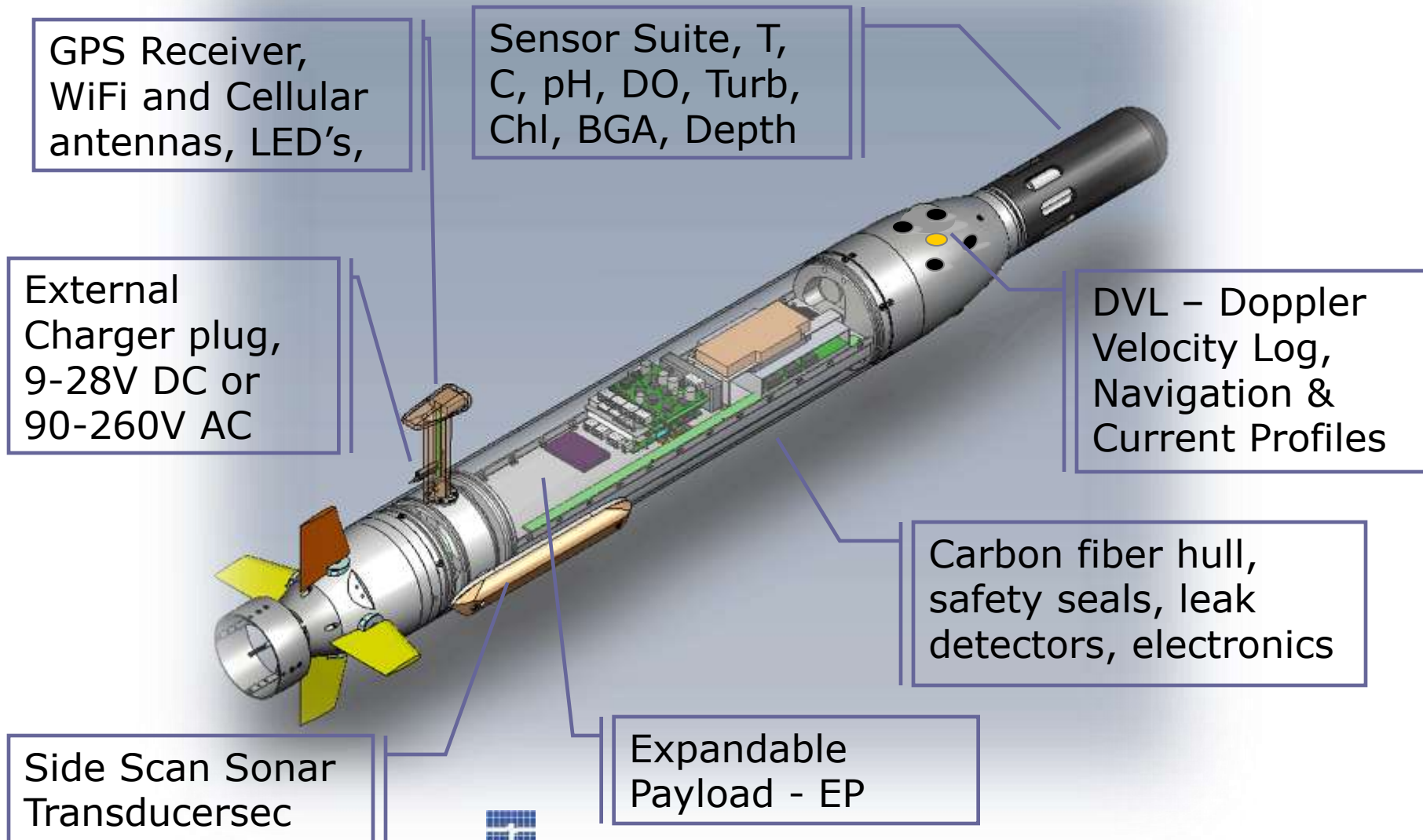
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The EcoMapper is a cost-effective tool for water quality, bathymetry, and bottom mapping / surveying

- Small, 1 Person-deployable
- Autonomous
- Ease of Use
- Sensor payload
- Open architecture

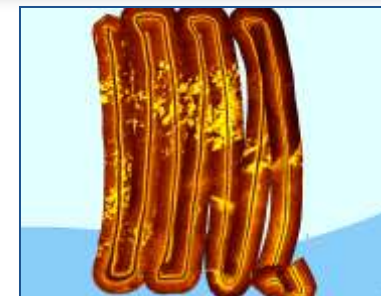
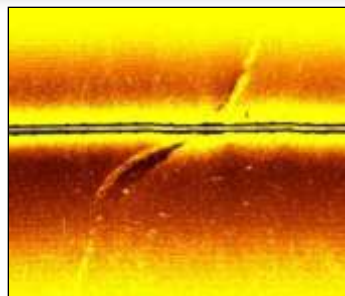




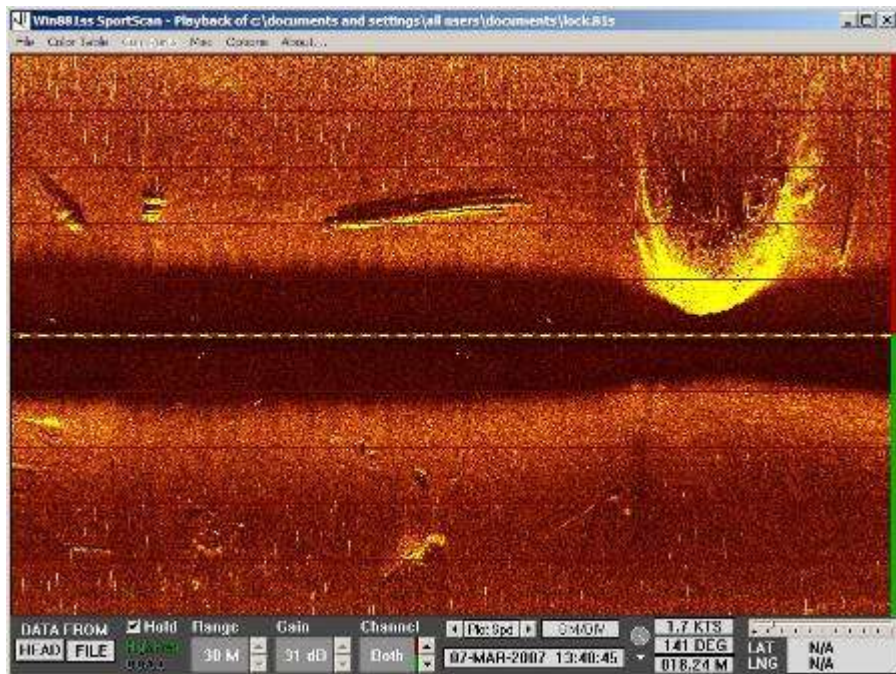


- Blue-Green Algae
 - Chlorophyll
 - Conductivity
 - Depth
 - Dissolved Oxygen
 - Nitrate
 - ORP (Redox)
 - PAR (Photo Active Rad)
 - pH
 - Resistivity
 - Rhodamine
 - Salinity
 - Specific Conductance
 - Temperature
 - Total Dissolved Solids
 - Turbidity
 - More.....
- Measure up to 18 Water Parameters simultaneously
 - Employs a YSI 6600V2-4 System
 - User installable/configurable sensors
 - Interchangeable and Field Replaceable

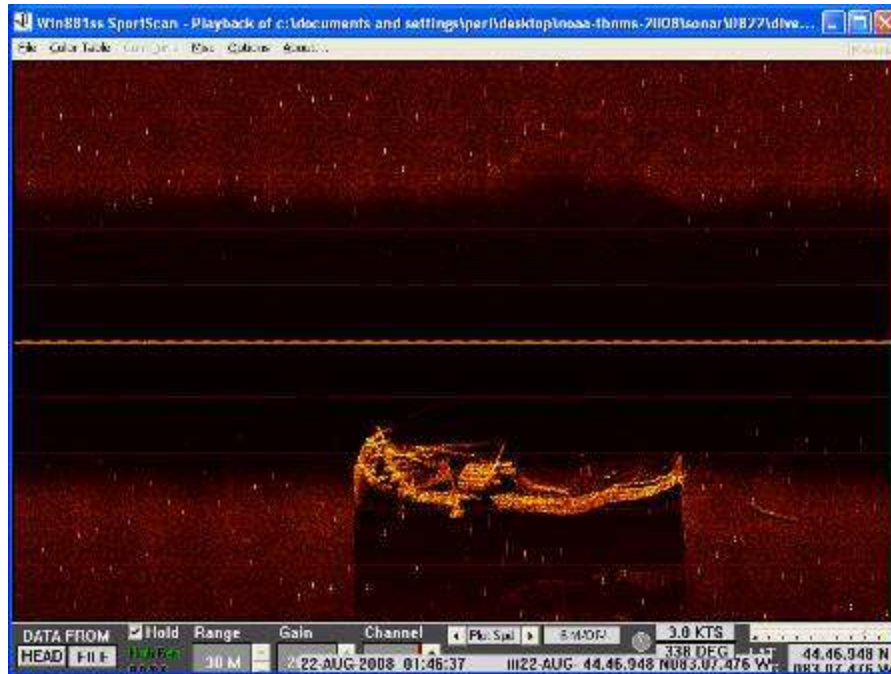




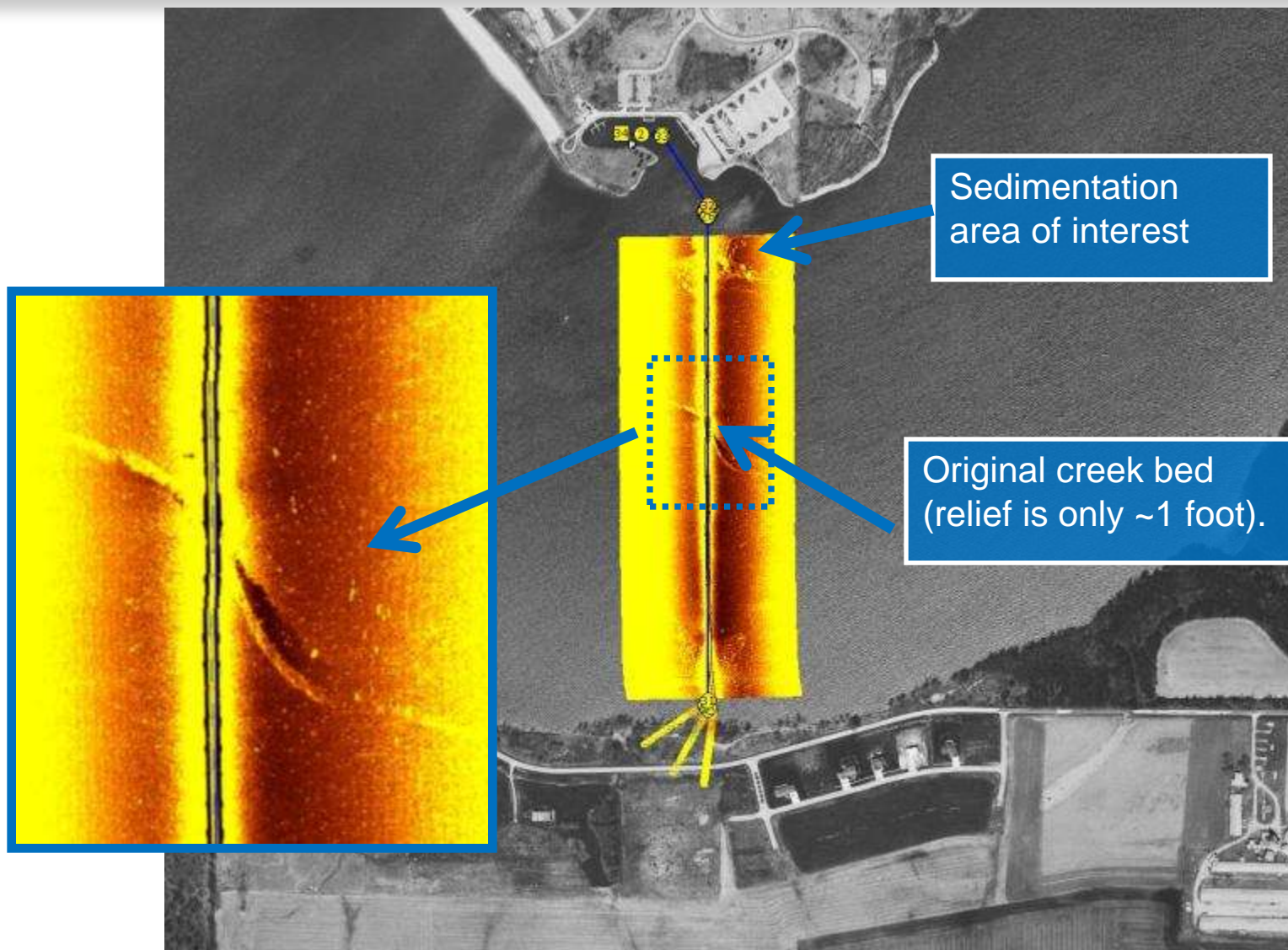
- Imagenex Sidescan (330KHz/800KHz)
- High Frequency <30m altitude,
- Low Frequency 120-30m altitude
- Range (beam swath) from 30-120m
- Best results by flying EcoMapper under the surface at a fixed depth at 1.5-2.5 knots.
- VectorMap Mosaicing software standard



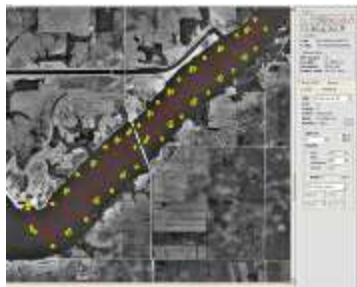
EcoMapper SSS Image of debris on the river bed in Pearl River, MS



EcoMapper SSS Image of shipwreck in Great Lakes



1.



2.



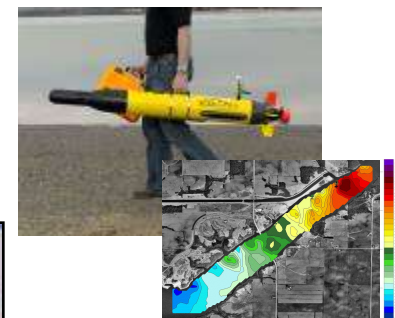
3.



4.



5.



1. Vector Map –
Point and click mission planning onto a geo-referenced map

2. UVC Software–
Start EcoMapper with key fob
Load mission in EcoMapper
UVC Software

3. Start Mission
Place vehicle in water and start mission

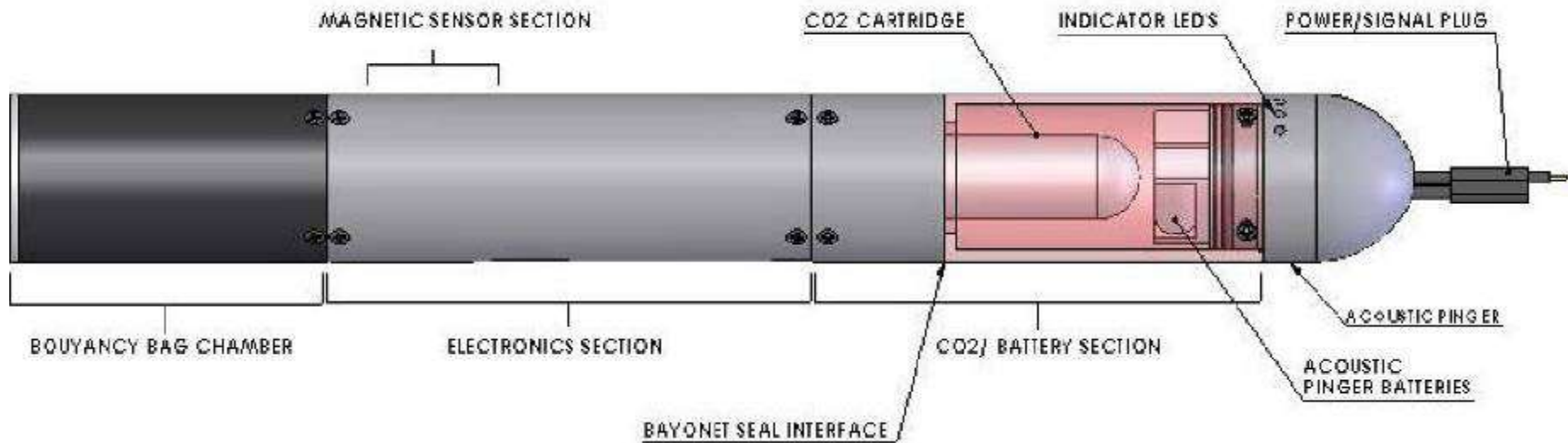
4. Remote Control –
When EcoMapper is on the surface and within range, view data and monitor progress or take manual control

5. Retrieve EcoMapper –
at planned PARK location and download data via Wi-Fi link

1. **3 internal leak detectors**. If triggered the vehicle will abort the mission, come to the surface, and employ park mode and remain within safety circle
2. **Location pinger**. If the vehicle becomes stuck or disabled at depth, a hydrophone can be used to locate submerged vehicle.
3. **UVC Safety Rules** (see next slide)
4. **Vacuum fixture** allows to test seals before all missions
5. **Pressure relief valves** in case of moisture getting into battery compartment
6. **Safety Tow Body**: towable pod that contains pinger, electronics, location LEDs, pressure sensor and large flotation device that will be triggered under specified conditions.

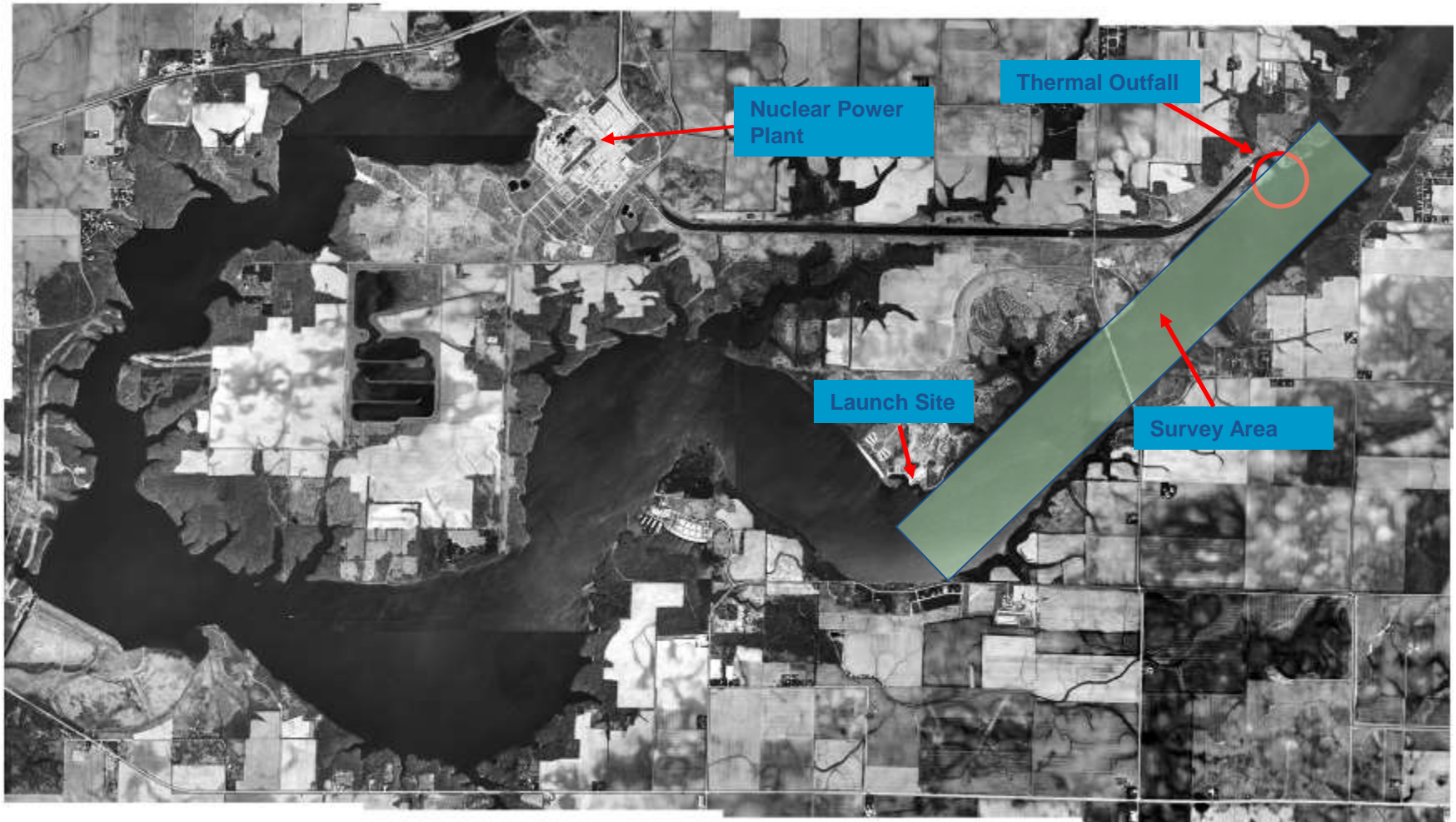


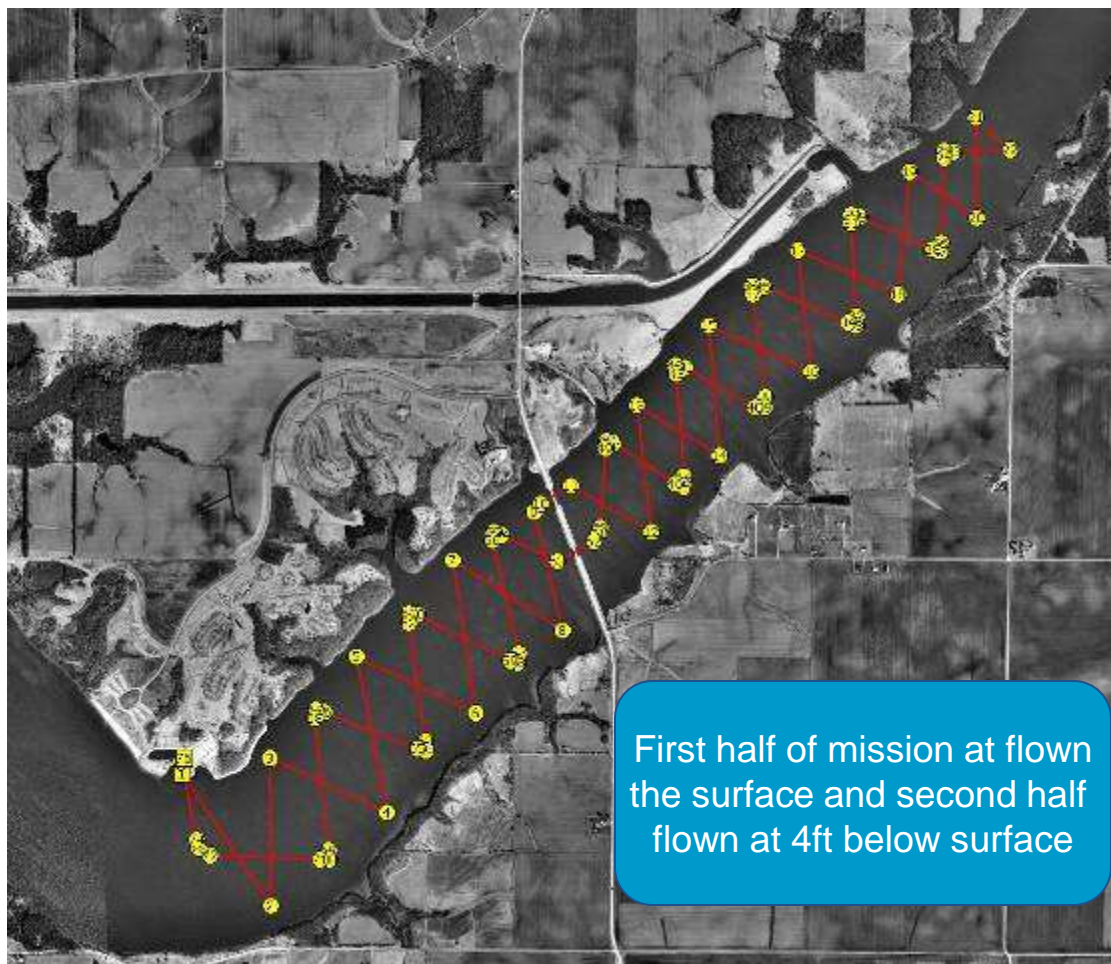




1. Enables Vehicle recovery from typical deployment hazards
2. Includes acoustic pinger for tracking
3. Simple autonomous operation
4. Reusable buoyancy bag
5. Simple CO2 cartridge system
6. 12 minute charge time



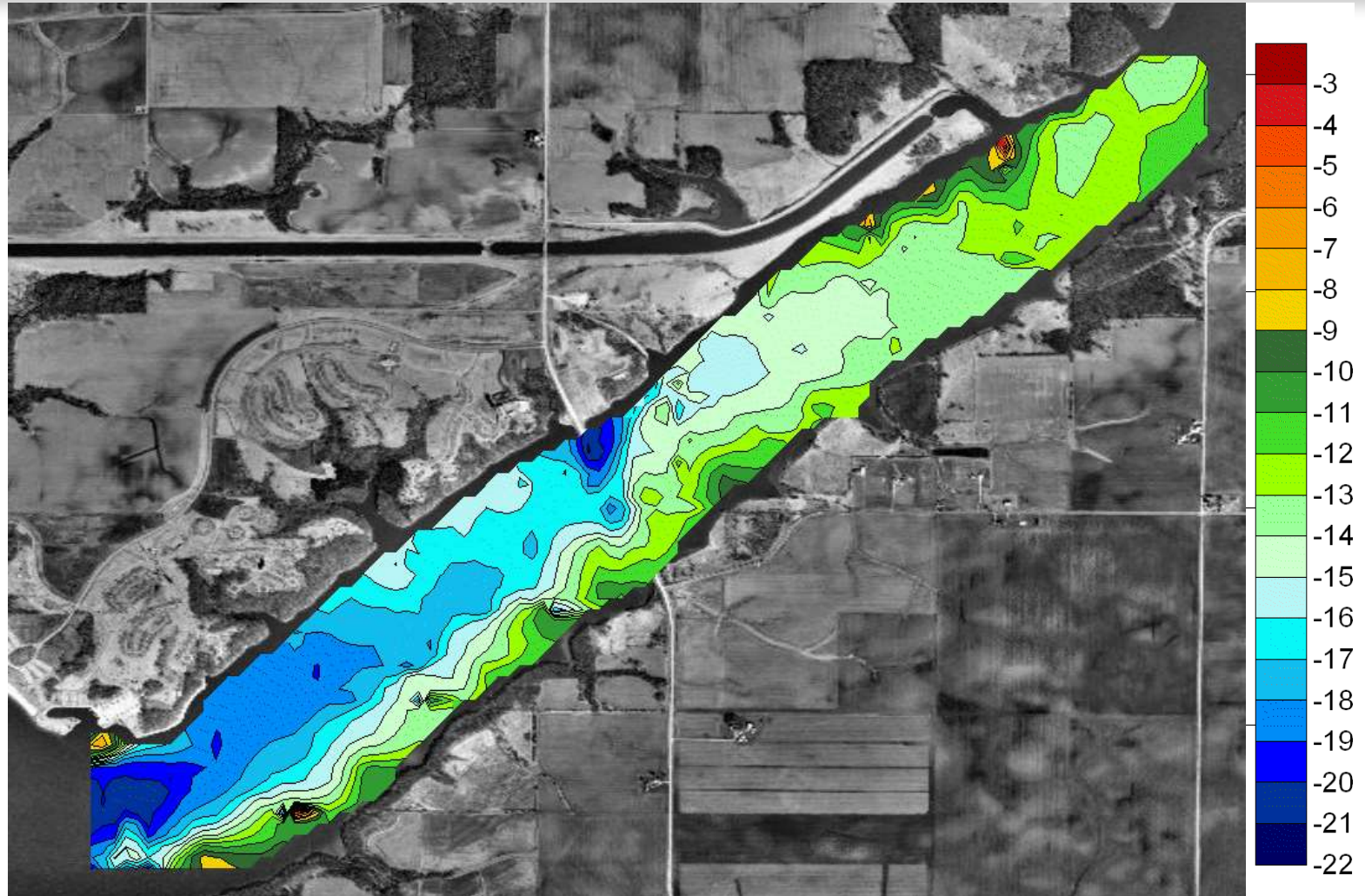




First half of mission at flow the surface and second half flow at 4ft below surface

Mission was 4:43 minutes plus 1 hour Park

Location	
Lat:	40.1761411496583
Long:	-88.7658708940397
Mission Info	
WP Count:	76
Length:	11.0966 mi
Duration:	05:43:55
Power Left:	387.32 WHr
Waypoints Buoy	
Layers Tracking	
WP:	Reference WP
Lat:	0
Long:	0
Time:	05:43:55
Dist:	11.0966 mi
Power:	0 WHr

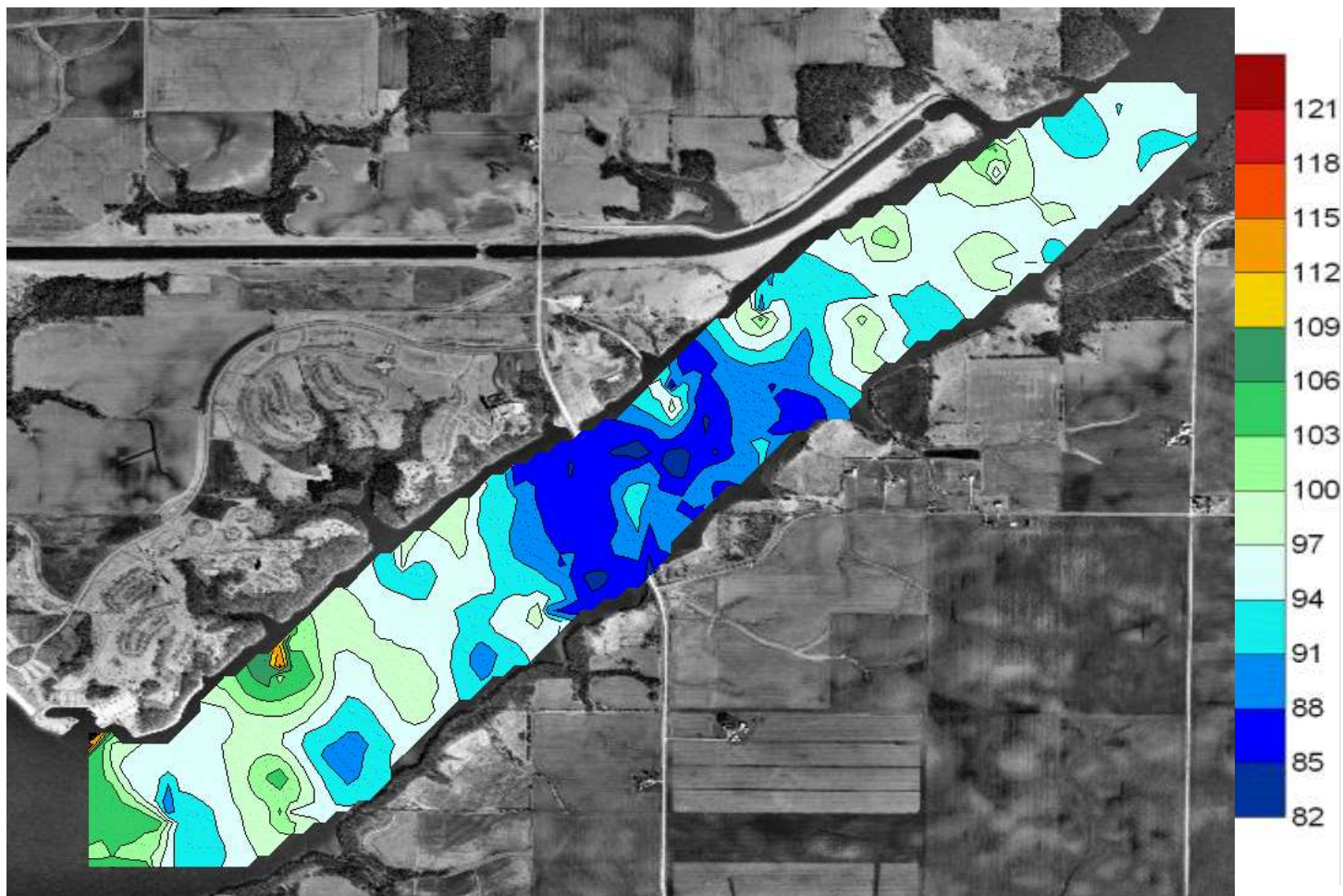


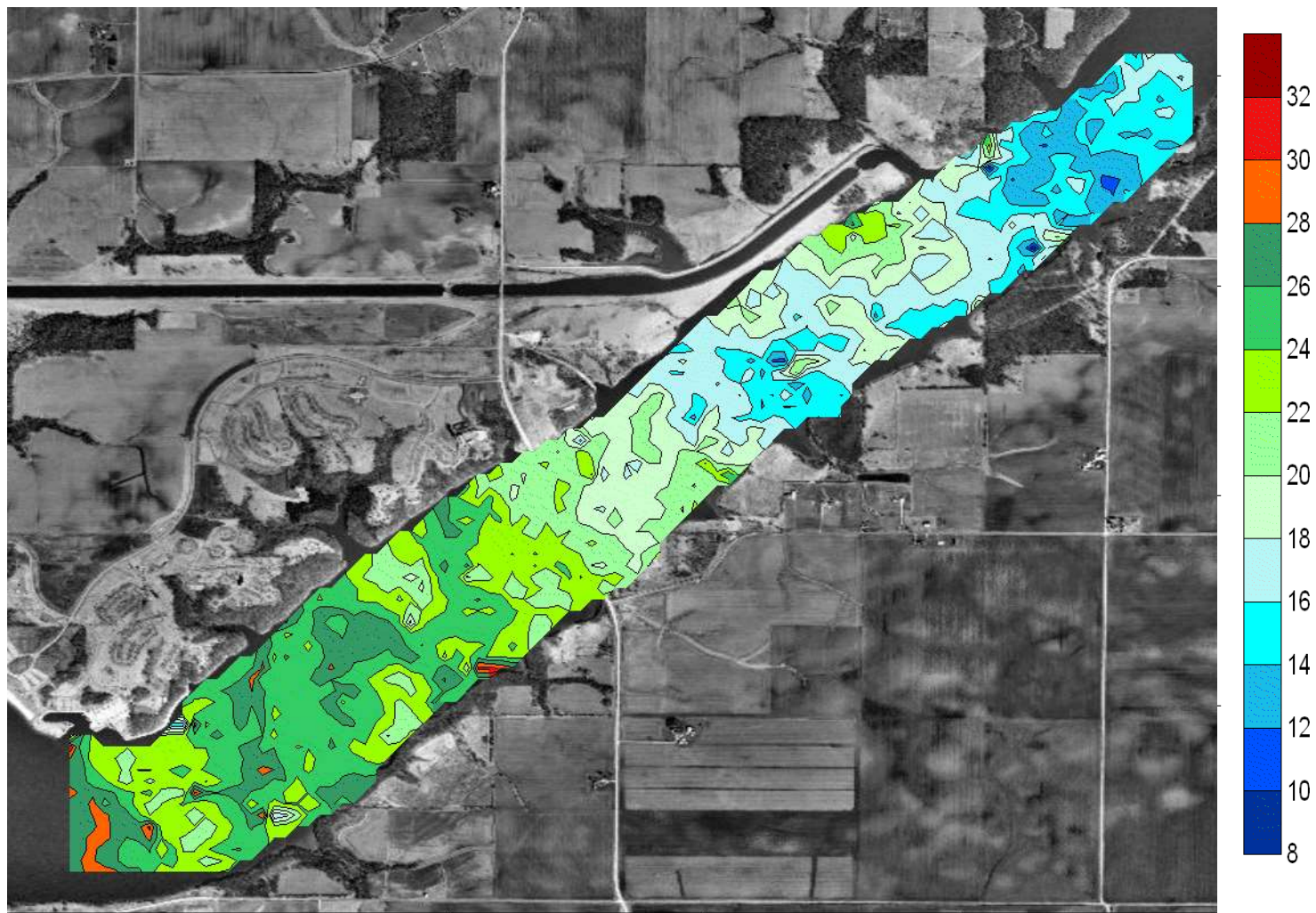
SURFACE TEMPERATURE



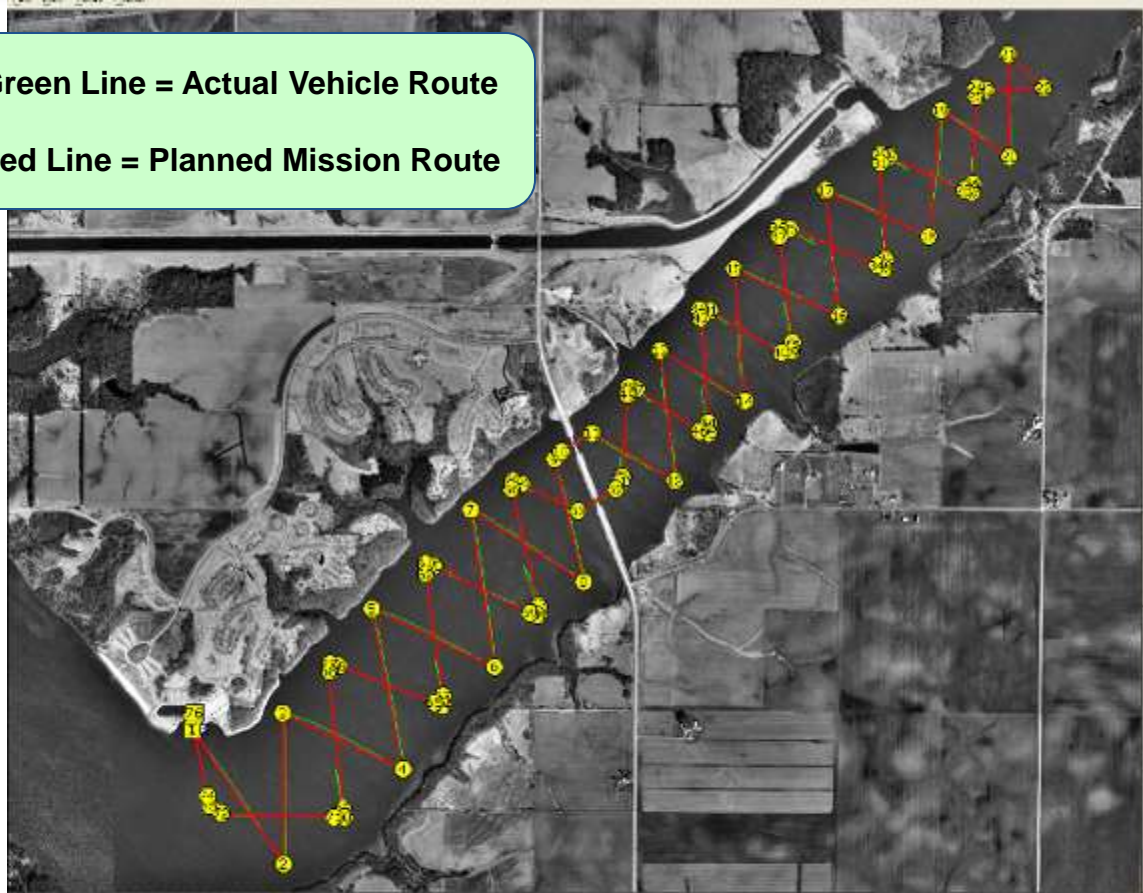
SUB-SURFACE TEMPERATURE (4')







Green Line = Actual Vehicle Route
Red Line = Planned Mission Route



Tools

Location
 Lat: 46.17492776036405
 Long: -88.2918154428530

Mission Info
 WP Count: 28
 Length: 11.3966 mi
 Duration: 05:43:55
 Power Left: 361.32 Whr

Waypoints | **Tools**

Layers | **Tracking**

WP: Reference WP
Lat: 0
Long: 0
Time: 00:43:00
Dist: 11.0566 mi
Power: 0 Whr

Speed: VC1 VC2
 2 100

Depth:
 DFS H: 0 ft
 IFD D: 0 ft
 InSubs A: 0 ft
 Sord: A: 0 ft

Park: 0 mins

Don't use sensor

Sent: [] [] [] []
Recv: [] [] [] []

ID	Latitude	Longitude	Time	Date	Num of Sats	GPS Speed	GPS True H	GPS Magne	C. Magne
1	40.149785	-88.80890	11:41:43 PM	5/6/2008	11	3.82	128.54	-2.0056723	204.2
2	40.149720	-88.80899	11:41:46 PM	5/6/2008	11	3.10	112.06	-2.0056723	210.4
3	40.149785	-88.80890	11:41:45 PM	5/6/2008	11	3.18	113.06	-2.0056723	208

Imagenex SportScan Side Scan Sonar

- Dual channel with a frequency of 330 kHz or 330 / 800 kHz
- 60m swath

